Shortest route

to success

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Public



Together we increase our impact on the world



At ORTEC... we make drivers happy!





What does that mean?

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We plan routes over roads We take into account traffic We don't make drivers wait (but we do give them breaks)

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In the VRPTW challenge

- •We drive as the crow flies
- •There is no traffic
- •We wait a lot
- (maybe that's why we don't take breaks)







What you get for 25 000 000 \$

Training machine learning models takes a lot of time and effort

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https://www.nature.com/articles/nature.2017.22858

The dataset



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The neural network



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The heavily tuned algorithm



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Conclusion

No machine learning here 🟵 Use good old human intelligence?









Fig. 1. Illustration of waiting times and time warps. **Proposition 1** (*Concatenation of two sequences*). Let $\sigma = \sigma$

 $(\sigma_i, \ldots, \sigma_j)$ and $\sigma' = (\sigma'_{i'}, \ldots, \sigma'_{j'})$ be two subsequences of visits. The concatenated subsequence $\sigma \oplus \sigma'$ is characterized by the following data:

$D(\sigma \oplus \sigma') = D(\sigma) + D(\sigma') + \delta_{\sigma_j \sigma'_i} + \Delta_{WT}$	(5)
$TW(\sigma \oplus \sigma') = TW(\sigma) + TW(\sigma') + \Delta_{TW}$	(6)
$E(\sigma \oplus \sigma') = \max\{E(\sigma') - \varDelta, E(\sigma)\} - \varDelta_{WT}$	(7)
$L(\sigma \oplus \sigma') = \min\{L(\sigma') - \varDelta, L(\sigma)\} + \varDelta_{TW}$	(8)
$C(\sigma \oplus \sigma') = C(\sigma) + C(\sigma') + c_{\sigma_j \sigma'_{i'}}$	(9)
$Q(\sigma \oplus \sigma') = Q(\sigma) + Q(\sigma')$	(10)
where $A = D(\sigma)$ $TW(\sigma) + \delta$, $A_{ii} = max(E(\sigma') - A_{ii} I(\sigma) 0)$	and

where $\Delta = D(\sigma) - TW(\sigma) + \delta_{\sigma_j \sigma'_{j'}}$, $\Delta_{WT} = \max\{E(\sigma') - \Delta - L(\sigma), 0\}$ and $\Delta_{TW} = \max\{E(\sigma) + \Delta - L(\sigma'), 0\}$.

Supporting time windows

- Use time-warp principle
- Cache computation for prefix and postfix
 of routes

(k!)4

• Use two-level hierarchy for fast queries in middle of route

 Penalty booster: increase penalty by 100% if no feasible solution found

Source: Vidal et al. 2012

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Initial heuristics

- 85% random:
 - Randomly order nodes
 - Split into routes using SPLIT algorithm (Vidal, 2012)
- 5% farthest, 5% nearest insertion:
 - Insert the node with shortest detour (given this is feasible)
 - If no feasible insertion, start new route with farthest/nearest node from depot
- 5% sweep:
 - Sort by angle to depot and add until capacity violated
 - For each route, sort customers with short time windows by time
 - For each route, insert customers with long time windows by shortest detour

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Offspring generation

Selective Route Exchange (SREX)

540 Y. Nagata and S. Kobayashi





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Fig. 1. Illustration of the SREX. σ_A^p and σ_B^p are parents. Routes S_A and S_B are represented as dotted lines, customer nodes $V_{A\setminus B}$ are represented by circles with x-mark, and the customer nodes in $V_{B\setminus A}$ are represented by double circles. σ_I^c and σ_{II}^c are intermediate offspring solutions obtained after Step 2.

Source: Nagata et al. 2010

Local search

•SWAP, RELOCATE, 2-OPT, 2-OPT* Moves between near neighbors Smart 'pre-checks' SWAP*, see next slide



SWAP*

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Exchange two nodes, insert at best position in other route





Cache top 3 insertion positions Exact for CVRP Approximate for VRPTW



Growing the neighborhood & population

Every 10K iterations Grow neighborhood by 5 Grow population size by 5

*Slightly different schedule for different instances

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Time (s)

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 $(\mathbf{k}!)^4$

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Results



(k!)

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