

The
automation of
the SET card
game

Wouter Kool

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Classification of
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Card Recognition Using Computer Vision

Wouter Kool

December 10, 2013

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A SET card

- **Quantity** - 1, 2 or 3
- **Fill** - open, half-filled or solid
- **Color** - red, purple or green
- **Shape**
 - **Ravensburger** - rectangle, tilda, oval
 - **NNN Games** - diamond, tilda, rounded rectangle

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A SET

Combination of three cards, such that each individual property equal or all different for the three cards

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A SET

Combination of three cards, such that each individual property equal or all different for the three cards

The goal

Finding SETs amongst 12 (or more) cards

Introduction: Example of a SET

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Figure : Example of a SET from the NNN Games edition.

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- How can SETs automatically be detected from an image using Computer Vision?

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- How can SETs automatically be detected from an image using Computer Vision?

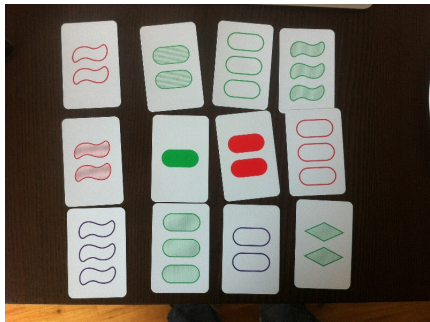


Figure : An image of 12 SET cards.

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Locating cards

Two options:

- **Top down approach** - using card borders.
- **Bottom up approach** - using the location of individual shapes.

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Locating cards

Two options:

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- **Bottom up approach** - using the location of individual shapes.

Classification of the cards

- **Shape** - comparison of shape contours
- **Fill and color** - classification models on features
- **Quantity** - follows from combining shapes

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- **Bottom up approach** - using the location of individual shapes.

Classification of the cards

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- **Fill and color** - classification models on features
- **Quantity** - follows from combining shapes

Finding SETs

$O(n^2)$ algorithm

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Top down approach

- 1 Finding contours of cards
- 2 Locating card corners
- 3 Extracting card image

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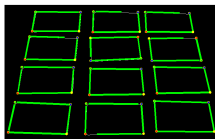
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Top down approach

- 1 Finding contours of cards
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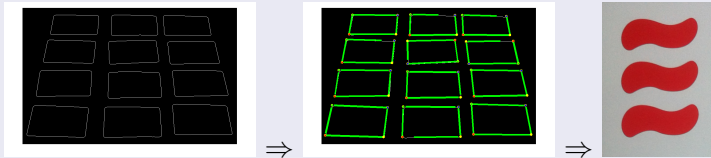
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Top down approach

- 1 Finding contours of cards
- 2 Locating card corners
- 3 Extracting card image

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Discussion

- Generally used method in literature
- Main disadvantage: cards may not overlap

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Bottom up approach

- 1 Finding contours in the image
- 2 Filtering contours on topological features
- 3 Finding the group of shape contours
- 4 Extracting shape images
- 5 Combining shapes to cards

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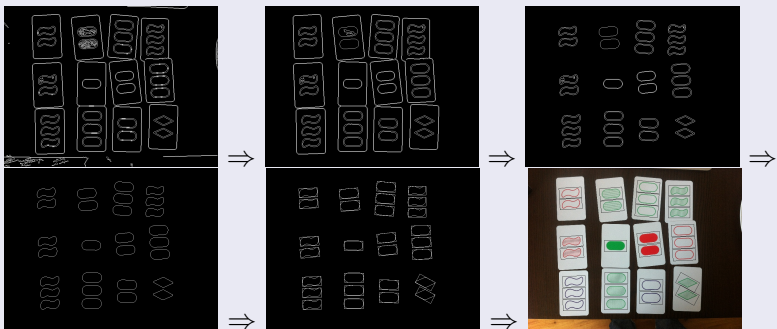
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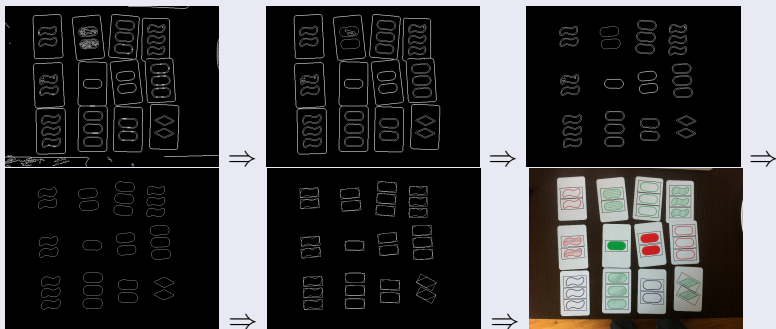
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Discussion

- Method works well: classification based on this
- Combining to cards done after classification

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Shape

Two options:

- Using image moments
- Using absolute image difference

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Shape

Two options:

- Using image moments
- Using absolute image difference

Fill and color

- 7 features for fill, 11 for color
- Feature set reduction (PCA)
- 4 classification models

Method: Classification of the cards

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Shape

Two options:

- Using image moments
- Using absolute image difference

Fill and color

- 7 features for fill, 11 for color
- Feature set reduction (PCA)
- 4 classification models

Quantity

Follows from combining shapes to cards

Method: Classification of the cards, the shape

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Idea

- Reference shapes for each brand
- Comparison gives error
- Match shapes for brand with lowest average error

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Idea

- Reference shapes for each brand
- Comparison gives error
- Match shapes for brand with lowest average error

Using image moments

$$I(A, B) = \sum_{i=1}^7 \left| \frac{1}{m_i^A} - \frac{1}{m_i^B} \right| \quad (1)$$

$m_i^A = \text{sign}(h_i^A) \cdot \log h_i^A$ and $m_i^B = \text{sign}(h_i^B) \cdot \log h_i^B$, h_i^A and h_i^B are the Hu-moments

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Using absolute image difference

Lowest error:  \Rightarrow  or  or .

Method: Classification of the cards, the fill

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Preprocessing

- Convert to grayscale
- Maximize contrast
- Extract region of interest

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Calculation of features

- **Mean luminance** - the mean of the pixel intensities.
- **Quantiles of the luminance distribution** - the 5%, 25%, 75% and 95%-quantiles of the distribution of the pixel intensities.
- **Mean absolute Laplacian** - the mean of the values obtained from applying the Laplacian operator on the matrix with pixel intensities.
- **Mean absolute difference to blurred image** - the mean of the absolute differences in pixel intensities between the image and a heavily blurred version of the image.

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Feature set reduction

- Find low dimensional representation of data
- Prevents overfitting in high dimensional space
- Relevant information should not be lost

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Feature set reduction

- Find low dimensional representation of data
- Prevents overfitting in high dimensional space
- Relevant information should not be lost

Principle component analysis

- Transformation of feature space
- First components represent most variance
- Better than feature subset selection

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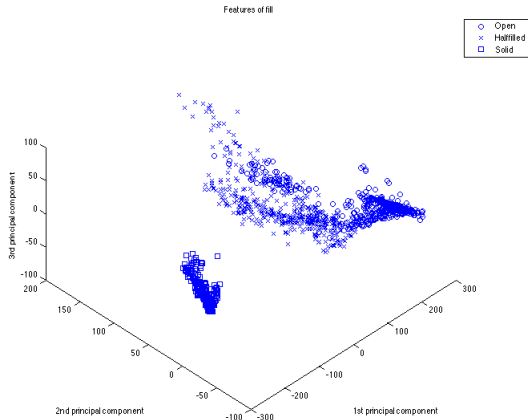
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3 principle components, NNN Games



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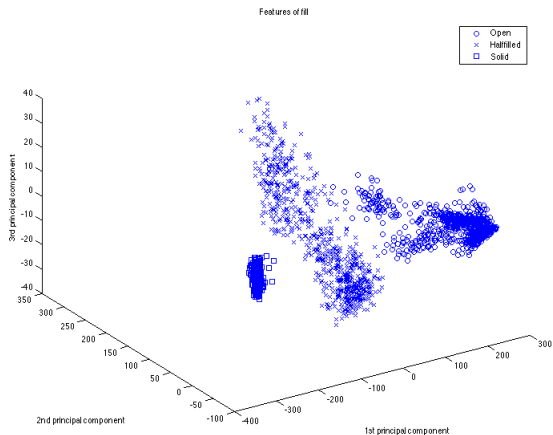
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3 principle components, Ravensburger



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Training of a classification model

- Training on a training set (discussed later)
- Training on features resulting from PCA

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Training of a classification model

- Training on a training set (discussed later)
- Training on features resulting from PCA

Classification models

- Support Vector Machines
- K-Nearest Neighbor
- Normal Bayes Classifier
- Gradient Boosted Trees

Method: Classification of the cards, the color

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Preprocessing

- Convert to colorspace: YCrCb
- Selecting pixels of interest

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Preprocessing

- Convert to colorspace: YCrCb
- Selecting pixels of interest

Calculation of features

- **Mean Cr and Cb** - the means of the Cr and Cb values of the pixels of interest.
- **Quantiles of the Cr and Cb distribution** - the 5%, 25%, 75% and 95%-quantiles of the distributions of the Cr and Cb values of the pixels of interest.
- **Lightness** - the 95%-quantile of the distribution of the Y values of the *full* image.

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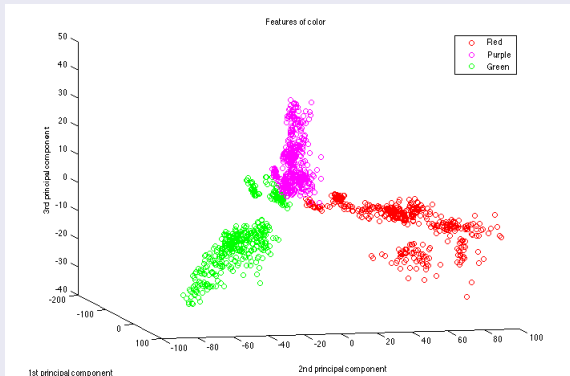
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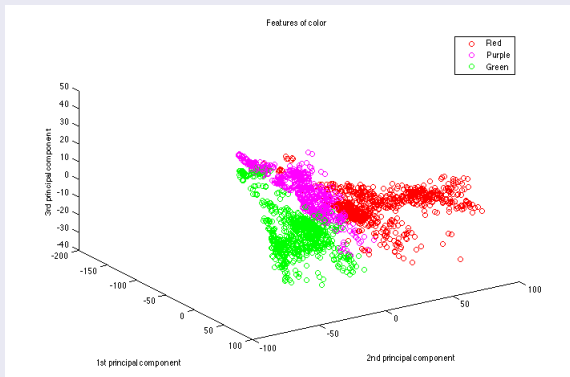
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Combining shapes

- Equal shape, fill and color
- Distance smaller than average width
- Recursion to label shapes
- Results in quantity and cards

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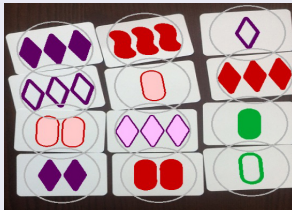
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Combining shapes

- Equal shape, fill and color
- Distance smaller than average width
- Recursion to label shapes
- Results in quantity and cards

Example



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Idea

- Each pair forms SET with exactly one card
- For each pair, check if third card available

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Idea

- Each pair forms SET with exactly one card
- For each pair, check if third card available

Implementation

- Build index with cards
- Iterate over pairs
- Property of third card for each pair:
 - Property equal \Rightarrow third card equal
 - Property different \Rightarrow third card remaining property
- Check if third card available and SET not already found

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Training set

- 2266 shape images for Ravensburger
- 1299 shape images for NNN Games

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Training set

- 2266 shape images for Ravensburger
- 1299 shape images for NNN Games

Experiment setup

- Shapes: static method using single reference shape
- Fill and color: 5-fold crossvalidation

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Shape

- Absolute image difference works best

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Shape

- Absolute image difference works best

Color and fill

- Generally more principle components result in higher accuracy
- SVM generally performs best

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- Absolute image difference works best

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- SVM generally performs best

Combined accuracy

Using SVM on all principle components

Edition	Color	Fill	Shape	All
Ravensburger	96.03 %	99.87 %	99.74 %	95.72 %
NNN Games	99.77 %	99.46 %	99.92 %	99.15 %

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The SET app

- Implementation in an iOS app
- Using OpenCV framework
- Corrective mechanism for errors

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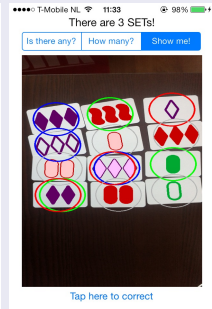
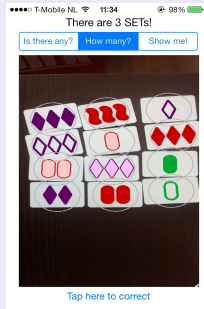
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The SET app

- Implementation in an iOS app
- Using OpenCV framework
- Corrective mechanism for errors

Screenshots



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Accuracy

- High accuracy for individual shape
- All 12 cards correct roughly with probability $0.957^{12 \cdot 2} = 0.350$ for RVB and $0.992^{12 \cdot 2} = 0.815$ for NNN

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In practice

- Indeed frequently around one shape incorrect
- Feedback mechanism required
- Occasionally 'clear' image incorrect so training set could be enlarged

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Future work

- Use of more texture descriptors from literature
- Use of color image normalization methods

The end

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Did you find these SETs?

